# **TCS**

## Multifunctional Hybrid Structure of SVC and Capacitive Grid-Connected Inverter (SVC//CGCI) for Active Power Injection and Nonactive Power Compensation

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Abstract-In this paper, the structure, coordinate control method, and parameter design of a hybrid system are proposed for active power injection and nonactive power (reactive, harmonic, and unbalance power) compensation. The proposed hybrid system consists of a static var compensator (SVC) in parallel with a capacitive-coupling gridconnected inverter (CGCI) (SVC//CGCI). In SVC//CGCI, the SVC part is used to dynamic compensate the reactive power and unbalance power, while the low rating CGCI part is used to inject active power, provide harmonic power and a fixed amount of capacitive reactive power. Compared with conventional inductive-coupling grid-connected inverter (IGCI), the CGCI can provide active, reactive and harmonic power with low rating of active inverter part. The cost of the SVC part is much lower than that of active inverter part, thus the reduction of inverter rating can lead to a decrease in the total cost of the SVC//CGCI. Therefore, the SVC//CGCI can be a cost effective solution for active power injection and nonactive power compensation. Finally, simulation and experimental results are provided to show the advantages and validity of the proposed SVC//CGCI in compared with the conventional IGCI and SVC//IGCI.

*Index Terms*—Active power injection, capacitive grid connected inverter (CGCI), harmonic current compensation, inductive coupling grid connected inverter (IGCI), reactive power compensation, static var compensator (SVC).

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## I. INTRODUCTION

T HE grid is the interconnection of different power systems, from high-voltage transmission systems to low-voltage distribution systems, from centralized generation to distributed generation, from utility control centers to end-user home-area networks, and from traditional energy resources to renewable generation energy resources [1]. However, the development of the smart grid brings many new challenges on power quality [2], especially in weak grid area the small power quality problem can lead to severe consequence. Therefore, the multifunctional gridconnected inverters have been paid more and more attentions for their benefits on power quality improvement and renewable power integration.

Traditionally, the task of inductive grid-connected inverters (IGCIs) is used to transfer active power from renewable energy resources to the power grid. However, the integration of uncontrollable resources, such as wind and solar energy, can also cause power quality problems to the grid. Therefore, apart from renewable integration function, many researchers suggest to embed the power quality enhancement function in the IGCIs. As the active power flow is orthogonal to the reactive power flow, it is economical to use the same inverter to transfer active and reactive power simultaneously. To attach reactive power and active power transfer, the different control strategies have been proposed for IGCIs [3]-[8]. However, the harmonic and unbalanced power compensation abilities have not been included in the above control methods [3]-[8]. To include reactive, harmonic and unbalanced compensation abilities, the more general control strategies have been proposed in [9]–[12], etc.

According to the cost study in [13]–[15], the cost of the IGCI or active power filter (APF) is about \$60/kVA and the costs of static var compensator (SVC) and passive power filter (PPF) are about \$18/kVA and \$5/kVA. From the cost reduction point of view, as the costs of the SVC and PPF are much lower than that of active inverter part, the reduction of active inverter part capacity can lead to a decrease in the total cost of hybrid topologies. The different hybrid systems have been reported in literatures, such as passive power filter in parallel with APF (PPF//APF) [16], [17], SVC in parallel with APF (SVC//APF) [18], SVC in parallel with static synchronous

0278-0046 © 2018 IEEE. Personal use is permitted, but republication/redistribution requires IEEE permission. See http://www.ieee.org/publications\_standards/publications/rights/index.html for more information. compensator (SVC//STATCOM) [19], SVC in series with hybrid SPF (SVC-HAPF) [20]–[24], SVC in parallel with HAPF (SVC//HAPF) [25], etc. In this paper, a new hybrid system: SVC in parallel with CGCI (SVC//CGCI) is proposed. Compared with [16]–[24], the proposed SVC//CGCI has lower inverter's voltage rating than the PPF//APF, SVC//APF, SVC//STATCOM, and lower inverter's current rating than the SVC-HAPF. Moreover, the proposed SVC//CGCI has considered the active power injection, which is not included in [16]–[25]. The contributions of the proposed SVC//CGCI can be listed from different points of view.

- From the characteristic point of view, the proposed SVC//CGCI combines the advantages of both SVC [26]– [28] and CGCI [29], [30], which address the inherent problems of them.
- 2) From the functionality point of view, the proposed SVC//CGCI can be used for both active power injection and nonactive power dynamic compensation simultaneously. However, both SVC and CGCI cannot obtain the aforementioned functions when using alone.
- 3) From the parameter design point of view, the proposed parameter design method includes the considerations of reactive power sharing between SVC//CGCI, active power injection and the harmonic currents rejection.
- 4) From the control point of view, the unique coordinate control of the SVC part and CGCI part is proposed to coordinate the SVC part and the CGCI part for active power injection and nonactive power.

In the following Section II, the circuit configuration of the three-phase three-wire SVC//CGCI are presented. Based on the circuit configuration, the operation principle and coordinated control between SVC and CGCI are proposed in Section III. Then, the parameter design method of the SVC//CGCI is given in Section IV. After that, to show the advantages of the proposed SVC//CGCI, the simulation comparisons of the IGCI, SVC//IGCI, and the proposed SVC//CGCI are provided in Section V. In Section VI, representative experimental results are given based on laboratory-scaled hardware prototype. Finally, conclusion will be drawn in Section VII.

## II. CIRCUIT CONFIGURATION OF THE THREE-PHASE SVC//CGCI

Fig. 1 shows the system topology of a three-phase three-wire SVC//CGCI. In this paper, the subscript "x" denotes phase  $x = a, b, c; v_{sx}, v_x$ , and  $v_{invx}$  are the source voltage, load voltage, and inverter voltage, respectively.  $i_{sx}, i_{Lx}$ , and  $i_{cx}$  are source current, load current, and compensating current, respectively. The SVC part of the SVC//CGCI consists of a coupling inductor  $L_c$ , a parallel capacitive  $C_{PF}$  and a thyristor-controlled reactor with an inductor  $L_{PF}$ . The CGCI part consists of coupling LC filter ( $L_p$  and  $C_p$ ), a two-level voltage source inverter (VSI) and a dc-link capacitor  $C_{DC}$ . The CGCI part has both low-voltage rating due to large voltage drop on LC and low-current rating due to the current divider between  $i_{cx1}$  and  $i_{cx2}$ .



Fig. 1. Circuit configurations of the SVC//CGCI.



Fig. 2. Power flow analysis for unbalanced power compensation.

## III. OPERATION PRINCIPLE AND COORDINATED CONTROL OF SVC//CGCI

In this section, the operation principle and coordinated control of SVC//CGCI are discussed and explained into the following three parts.

- 1) Part A: SVC part control.
- 2) Part B: CGCI part control.
- 3) Part C: The overall control block.

## A. Operation Principle and Control of the SVC Part

The SVC part of SVC//CGCI is used to dynamically compensate the fundamental load unbalanced and reactive power by controlling its firing angles. The key concept of the SVC part control can be described in Section III-A1. The controls of the SVC part in delta connection are explained in Section III-A2.

1) Operation Principle and Concept of SVC Part: In this paper, the study of the proposed SVC//CGCI is based on balanced three-phase source voltage assumption. For the three-phase three-wire system, the unbalanced source active power can be automatically controlled to be balanced when the unbalanced reactive power is compensated to be balanced [24], [26]. Fig. 2 shows the power flow analysis of SVC//CGCI compensation.

The phase fundamental source apparent power is defined as:  $S_{sx} = P_{sx} + jQ_{sx} = \overrightarrow{V}_{sx} \cdot \overrightarrow{I}_{sxf}^*$ , where the note "\*" denotes the complex conjugate. In Fig. 2, the sum of  $\overrightarrow{I}_{sxf}^*$  can be expressed as [26]

$$\vec{I}_{saf}^{*} + \vec{I}_{sbf}^{*} + \vec{I}_{scf}^{*} = \frac{P_{sa} + jQ_{sa}}{\vec{V}_{saf}} + \frac{P_{sb} + jQ_{sb}}{\vec{V}_{sbf}} + \frac{P_{sc} + jQ_{sc}}{\vec{V}_{scf}} = 0$$
(1)

where  $\overrightarrow{I}_{saf}$ ,  $\overrightarrow{I}_{sbf}$ , and  $\overrightarrow{I}_{scf}$  are the fundamental source current phasors.  $\overrightarrow{V}_{saf}$ ,  $\overrightarrow{V}_{sbf}$ , and  $\overrightarrow{V}_{scf}$  are the fundamental source voltage phasors.  $\overrightarrow{V}_{saf}$  is set to be the reference phasor, so  $\overrightarrow{V}_{saf} = \overline{V}_{sxf} \angle 0^{\circ}$ ,  $\overrightarrow{V}_{sbf} = \overline{V}_{sxf} \angle -120^{\circ}$ , and  $\overrightarrow{V}_{scf} = \overline{V}_{sxf} \angle 120^{\circ}$ , where  $1\angle -120^{\circ} = -1/2 - j\sqrt{3}/2$ and  $1\angle 120^{\circ} = -1/2 + j\sqrt{3}/2$ ,  $V_{sxf}$  is the root-mean-square (RMS) value of the source voltage. Simplifying (1), one can get

$$\left(2P_{sa} - P_{sb} - \sqrt{3}Q_{sb} - P_{sc} + \sqrt{3}Q_{sc}\right)$$
  
+  $j\left(2Q_{sa} - Q_{sb} + \sqrt{3}P_{sb} - Q_{sc} - \sqrt{3}P_{sc}\right) = 0$  (2)

In (2), both real part and imaginary part are equal to zero. Thus, the following relationship can be obtained as

$$2P_{sa} - P_{sb} - \sqrt{3}Q_{sb} - P_{sc} + \sqrt{3}Q_{sc} = 0$$
  
$$2Q_{sa} - Q_{sb} + \sqrt{3}P_{sb} - Q_{sc} - \sqrt{3}P_{sc} = 0.$$
 (3)

If the source reactive power is compensated to be balanced by SVC part as (4), the source active power can be balanced as (5).

$$Q_{sa} = Q_{sb} = Q_{sc} = Q_{LC} \tag{4}$$

where  $Q_{sx}$  is source reactive power,  $Q_{LC}$  is the fixed value which is provided by the coupling *LC* of CGCI part. By substituting (4) into (3), the relationship of the three-phase source active power can be obtained as

$$P_{sa} = P_{sb} = P_{sc}.$$
 (5)

Based on the analysis of (1)–(5), it can be concluded that the source active power can become balanced once the reactive power is compensated to be balanced.

2) SVC Part Control: The purpose of this part is to obtain the firing angle  $(\alpha_{xy})$  of the SVC part to compensate the phase source reactive power  $Q_{sx}$  to equal  $Q_{LC}$ , so that the left small  $Q_{LC}$  can be compensated by CGCI. Moreover, the SVC part can help to balance the source active power. The compensating reactive power passing through SVC part can be expressed as follows:

$$Q_{c1x} = -(Q_{Lx} - Q_{LC})$$
(6)

where the  $Q_{c1x}$  are the phase compensating reactive power. The line to line reactive power passing through the SVC part can be

expressed as follows:

$$\begin{bmatrix} Q_{c1ab} \\ Q_{c1bc} \\ Q_{c1ca} \end{bmatrix} = \begin{bmatrix} Q_{c1c} - Q_{c1a} - Q_{c1b} \\ Q_{c1a} - Q_{c1b} - Q_{c1c} \\ Q_{c1b} - Q_{c1c} - Q_{c1a} \end{bmatrix}$$
$$= \begin{bmatrix} Q_{La} + Q_{Lb} - Q_{Lc} - Q_{LC} \\ Q_{Lb} + Q_{La} - Q_{La} - Q_{LC} \\ Q_{Lc} + Q_{La} - Q_{Lb} - Q_{LC} \end{bmatrix}$$
(7)

where  $Q_{LC}$  is the small and fixed reactive power provided by LC part of CGCI, which can be expressed as follows:

$$Q_{LC} = \frac{\bar{V}_x^2}{X_{L_P} - X_{C_P}}$$
(8)

where  $\bar{V}_x$  is the RMS value of load voltage which can be obtained in real time as  $\bar{V}_x = ||v_L||/\sqrt{3} = \sqrt{v_a^2 + v_b^2 + v_c^2}/\sqrt{3}$ [22].  $X_{Lp}$  and  $X_{Cp}$  are the impedances of  $L_P$  and  $C_P$ .

The purpose of the SVC part is used to compensate the fundamental reactive and unbalanced power by providing different  $\alpha_{xy}$  for each phase. To obtain  $\alpha_{xy}$ , the SVC part impedance  $X_{xy}$  in real-time is calculated as follows:

$$\begin{bmatrix} X_{ab} \\ X_{bc} \\ X_{ca} \end{bmatrix} = \begin{bmatrix} \frac{V_{ab}^2}{Q_{c1ab}} \\ \frac{V_{bc}^2}{Q_{c1ca}} \\ \frac{V_{ca}^2}{Q_{c1ca}} \end{bmatrix} = \begin{bmatrix} \frac{3 \cdot V_x^2}{Q_{c1ab}} \\ \frac{3 \cdot \bar{V}_x^2}{Q_{c1ca}} \\ \frac{3 \cdot \bar{V}_x^2}{Q_{c1ca}} \end{bmatrix} = \begin{bmatrix} \frac{3 \cdot V_x^2}{Q_{La} + Q_{Lb} - Q_{Lc} - Q_{Lc}} \\ \frac{3 \cdot \bar{V}_x^2}{Q_{Lb} + Q_{La} - Q_{La} - Q_{Lc}} \\ \frac{3 \cdot \bar{V}_x^2}{Q_{Lc} + Q_{La} - Q_{Lb} - Q_{Lc}} \end{bmatrix}$$
(9)

where  $V_{xy}$  and  $V_x$  are the RMS values of the line-to-line and phase load voltage, respectively,  $Q_{Lx}$  is the phase load reactive power. The  $V_x$  and  $Q_{Lx} \approx -\bar{q}_{Lx}/2$  [21]–[24] can be calculated in real-time as follows:

$$\begin{bmatrix} q_{La} \\ q_{Lb} \\ q_{Lc} \end{bmatrix} = \begin{bmatrix} v_{\mathbf{a}} \cdot i_{La}^{D} - v_{\mathbf{a}}^{D} \cdot i_{La} \\ v_{\mathbf{b}} \cdot i_{Lb}^{D} - v_{\mathbf{b}}^{D} \cdot i_{Lb} \\ v_{\mathbf{c}} \cdot i_{Lc}^{D} - v_{\mathbf{c}}^{D} \cdot i_{Lc} \end{bmatrix}$$
(10)

$$V_x = \|v\| / \sqrt{3} = \sqrt{v_a^2 + v_b^2 + v_c^2} / \sqrt{3}$$
(11)

where  $v_x^D$  and  $i_{Lx}^D$  are obtained by delaying  $v_x$  and  $i_{Lx}$  by a phase angle of 90°.  $q_{Lx}$  is the phase instantaneous reactive power. Then,  $Q_{Lx} \approx -\bar{q}_{Lx}/2$  is obtained by passing  $q_{Lx}$  in (10) through low-pass filters. ||v|| is the norm of the three-phase instantaneous load voltage. After obtaining the  $X_{xy}$  through (7)– (11), the  $\alpha_{xy}$  is determined by solving the following equation.

$$\begin{bmatrix} X_{ab}(\alpha_{ab}) \\ X_{bc}(\alpha_{bc}) \\ X_{ca}(\alpha_{ca}) \end{bmatrix} = \begin{bmatrix} \frac{\pi X_{L_{\rm PF}} X_{C_{\rm PF}}}{X_{C_{\rm PF}} [2\pi - 2\alpha_{ab} + \sin(2\alpha_{ab})] - \pi X_{L_{\rm PF}}} + X_{L_c} \\ \frac{\pi X_{L_{\rm PF}} X_{C_{\rm PF}}}{X_{C_{\rm PF}} [2\pi - 2\alpha_{bc} + \sin(2\alpha_{bc})] - \pi X_{L_{\rm PF}}} + X_{L_c} \\ \frac{\pi X_{L_{\rm PF}} X_{C_{\rm PF}}}{X_{C_{\rm PF}} [2\pi - 2\alpha_{ca} + \sin(2\alpha_{ca})] - \pi X_{L_{\rm PF}}} + X_{L_c} \end{bmatrix}$$
(12)

where  $X_{L_c}$ ,  $X_{C_{\text{PF}}}$ , and  $X_{L_{\text{PF}}}$  are the impedances of the coupling inductor, the SVC capacitor, and inductor, respectively. With the calculated  $X_{xy}$  from (7)–(11), the  $\alpha_{xy}$  can be determined by solving (12). The details can be found in Section III-C.

#### B. Operation Principle and Control of CGCI Part

The operation principle and power range of the CGCI part is provided as Section III-B1. The control of CGCI is explained in Section III-B2.

1) Operation Principle and Power Range of CGCI Part: The inverter of CGCI is used to inject active power and reactive power at the fundamental frequency. The injected current from the CGCI and the output voltage of the VSI is given as follows:

$$I_{cx2f} = I_{cx2fp} + j \cdot I_{cx2fq} \tag{13}$$

$$V_{invxf} = \overrightarrow{V}_{xf} + X_{LC} \cdot \overrightarrow{I}_{cx2f}$$
  
=  $\overrightarrow{V}_{xf} + X_{LC} \cdot (\overrightarrow{I}_{cx2fp} + j\overrightarrow{I}_{cx2fq})$  (14)

where  $I_{cx2fp}$  and  $I_{cx2fq}$  are the fundamental active and reactive current that injects or absorbs from the grid.

Based on the above (13) and (14), the injected active power and reactive power by CGCI part can be expressed as follows:

$$S_{cx2f} = \overrightarrow{V}_{xf} \overrightarrow{I}_{cx2f}^* = \overrightarrow{V}_{xf} \cdot \left(\frac{\overrightarrow{V}_{invxf} - \overrightarrow{V}_{xf}}{jX_{LC}}\right)^*$$
$$= V_{xf} \cdot \left(\frac{(V_{invxf} + jV_{invxf}) - V_{xf}}{jX_{LC}}\right)^*$$
$$= V_{xf} \cdot \left(\frac{V_{invxf}}{X_{LC}} + j\frac{V_{invxf} - V_{xf}}{X_{LC}}\right)$$
$$= \frac{V_{xf}V_{invxf}}{X_{LC}} + j \cdot \left(\frac{V_{xf}V_{invxf}}{X_{LC}} - \frac{V_{xf}^2}{X_{LC}}\right)$$
$$= P_{cx2f} + jQ_{cx2f}$$
(15)

where \* is the conjugate value,  $V_{invxf}$  and  $V_{xf}$  are the fundamental inverter voltage and load voltage. Based on (15), the ratio of  $V_{invxf}/V_{xf}$  can be expressed as follows:

$$\frac{V_{\text{inv}xf}}{V_{xf}} = \sqrt{\frac{P_{cx2f}^2}{S_{\text{base}}} + \left(\frac{Q_{cx2f}}{S_{\text{base}}} - 1\right)^2}$$
(16)

where  $S_{\text{base}}$  is the base power of CGCI which can be expressed as follows:

$$S_{\text{base}} = \frac{V_{xf}^2}{X_{LC}} \tag{17}$$

where  $X_{LC}$  is the fundamental coupling impedance of the CGCI. Based on (16) and (17), the ratio of  $V_{\text{inv}xf}/V_{xf}$  in term of  $P_{cx2f}$  and  $Q_{cx2f}$  can be plotted as Fig. 3.

In Fig. 3, at the fundamental frequency, the coupling LC of CGCI part is used to compensate fixed amount of reactive power  $(Q_{cx2f} = S_{base})$ , and the  $V_{invxf}$  is used to inject active power.

2) CGCI Part Control: The purpose of the CGCI part is to inject active power  $P_{cx}^* = P_{cx2f}$ , and compensate the harmonic power and reactive power left by the SVC part. However, to avoid the mistuning problem of the SVC part, the CGCI is controlled to limit the compensating current  $i_{cx}$  (instead of inverter current  $i_{cx2}$ ) to the reference value  $i_{cx}^*$ . The  $i_{cx}^*$  can be calculated



Fig. 3. Ratio of  $V_{\text{inv}xf}/V_{xf}$  in term of  $P_{cxf}/S_{\text{base}}$  and  $Q_{cx2f}/S_{\text{base}}$ .

through the well-known instantaneous p-q theory [31] as

$$\begin{bmatrix} i_{ca}^{*} \\ i_{cb}^{*} \\ i_{cc}^{*} \end{bmatrix} = \sqrt{\frac{2}{3}} \cdot \frac{1}{v_{\alpha}^{2} + v_{\beta}^{2}} \begin{bmatrix} 1 & 0 \\ -1/2 & \sqrt{3}/2 \\ -1/2 & -\sqrt{3}/2 \end{bmatrix} \cdot \begin{bmatrix} v_{\alpha} & -v_{\beta} \\ v_{\beta} & v_{\alpha} \end{bmatrix}$$

$$\begin{bmatrix} \tilde{p}_{\alpha\beta} + 3P_{cx}^{*} \\ q_{\alpha\beta} \end{bmatrix}$$
(18)

where  $P_{cx}^*$  is reference phase injected active power, and the total reference active power is  $3P_{cx}^*$  for three-phase system,  $\tilde{p}_{\alpha\beta}$  is three-phase instantaneous harmonic active power,  $q_{\alpha\beta}$  is the three-phase instantaneous reactive power which include harmonic component  $\tilde{q}_{\alpha\beta}$  and dc component  $\bar{q}_{\alpha\beta}$ . As the reference compensating current  $i_{cx}^*$  is calculated from  $\tilde{p}_{\alpha\beta}$  and  $q_{\alpha\beta}$  (included  $\tilde{q}_{\alpha\beta}$  component), the three-phase  $\tilde{p}_{\alpha\beta}$  and  $\tilde{q}_{\alpha\beta}$  fluctuation can be suppressed by limiting the compensating current  $i_{cx}$ . The major part of  $\bar{q}_{\alpha\beta}$  is shared by SVC part, while the remaining amount of  $\bar{q}_{\alpha\beta}$  for three phase is compensated by *LC* part of CGCI. The  $p_{\alpha\beta}$  and  $q_{\alpha\beta}$  can be expressed as follows:

$$\begin{bmatrix} p_{\alpha\beta} \\ q_{\alpha\beta} \end{bmatrix} = \begin{bmatrix} v_{\alpha} & v_{\beta} \\ -v_{\beta} & v_{\alpha} \end{bmatrix} \cdot \begin{bmatrix} i_{\alpha} \\ i_{\beta} \end{bmatrix}.$$
 (19)

In (18) and (19), the voltages  $(v_{\alpha} \text{ and } v_{\beta})$  and currents  $(i_{\alpha} \text{ and } i_{\beta})$  in  $\alpha - \beta$  plane are transformed from *a-b-c* frames by

$$\begin{bmatrix} v_{\alpha} \\ v_{\beta} \end{bmatrix} = \begin{bmatrix} 1 & -1/2 & -1/2 \\ 0 & \sqrt{3}/2 & -\sqrt{3}/2 \end{bmatrix} \cdot \begin{bmatrix} v_a \\ v_b \\ v_c \end{bmatrix}$$
(20)

$$\begin{bmatrix} i_{\alpha} \\ i_{\beta} \end{bmatrix} = \begin{bmatrix} 1 & -1/2 & -1/2 \\ 0 & \sqrt{3}/2 & -\sqrt{3}/2 \end{bmatrix} \cdot \begin{bmatrix} i_{La} \\ i_{Lb} \\ i_{Lc} \end{bmatrix}$$
(21)

where  $v_x$  and  $i_{Lx}$  are load voltage and current signals.

#### C. Overall Control Block of SVC//CGCI

The overall control block of the proposed SVC//CGCI is provided in Fig. 4. According to Fig. 4 and the SVC part control in Section III-A, (10) and (11) are used to calculate the load reactive power  $q_{Lx}$  and load voltage  $V_x$ . Then, SVC part impedance



 $X_{xy}$  can be obtained from (9) with the help of  $Q_{Lx} \approx -\bar{q}_{Lx}/2$ and reactive power of the coupling *LC* of CGCI part in (8). After that, by comparing the impedance  $X_{xy}$  in (9) and (12), the firing angle  $\alpha_{xy}$  can be obtained. As the (12) does not have a closedform solution, a lookup table has been installed to directly obtain the firing angle  $\alpha_{xy}$  with known  $X_{xy}$ . By comparing the precalculated  $\alpha_{xy}$  of the load voltage  $\theta_{xy}$ , the trigger signals for the thyristor of the SVC can be obtained by using a phase-lock loop.

Based on Fig. 4 and the CGCI part control in Section-B, the load voltage and current ( $v_x$  and  $i_{Lx}$ ) in *a-b-c* frame are transformed to  $\alpha - \beta$  frame through the (20) and (21). By using the instantaneous p-q theory, the instantaneous active power and reactive power in  $\alpha - \beta$  frame can be calculated through (19).

With the help of the high pass filter and (18), the load reactive power and harmonic active power can be transferred to  $i_{cx}^*$ . Through the current hysteresis PWM control method, the trigger signals of the CGCI can be generated by comparing the  $i_{cx}$  with  $i_{cx}^*$ .

## IV. PARAMETER DESIGN OF THE PROPOSED SVC//CGCI

In this section, a parameter design method is discussed and proposed in two parts. In Section IV-A, the parameter design of the  $C_P$  and  $L_p$  is proposed for the CGCI part. In Section IV-B, the design of  $L_c$ ,  $C_{\rm PF}$ , and  $L_{\rm PF}$  is given for the SVC part.

## A. Design of $C_P$ and $L_P$

According to Fig. 3 and (15), the injected active power can be used to determinate the  $X_{LC}$ . Based on (15), the  $X_{LC}$  is designed as follows:

$$X_{LC} = \frac{V_{xf}V_{\text{inv}xf}}{P_{cx2f(\text{Max})}} \approx \frac{V_{xf}V_{\text{DC}}}{\sqrt{6} \cdot P_{cx2f(\text{Max})}}$$
(22)

where  $P_{cx2f(\max)}$  is the maximum injected active power can be provided by CGCI,  $V_{xf}$  is the load voltage,  $V_{DC}$  is designed dc-link voltage. From another perspective, the  $X_{LC}$  can be expressed as the impedance of coupling components of CGCI

$$X_{LC} = X_{L_p} - X_{C_P} = \omega \cdot L_p - 1/\omega \cdot C_p$$
(23)

where  $\omega$  is the angular frequency  $\omega = 2\pi f$ . In (23), the impedance of  $X_{Cp}$  is much larger than  $X_{Lp} (X_{Cp} >> X_{Lp})$ . Therefore, based on (22) and (23), the  $C_p$  can be designed as

$$C_p \approx \frac{\sqrt{6} \cdot P_{cxf(\text{Max})}}{2\pi f \cdot V_{xf} V_{\text{DC}}}.$$
(24)

The coupling inductor  $L_P$  of CGCI is used to reduce the dominant harmonic order  $n_1$  of the loads. By tuning the zero impedance point of  $X_{LC}(n_1\omega) = 0$  in (23) at the dominant harmonic order  $n_1$ , the  $L_p$  can be expressed as follows:

$$L_p \approx \frac{1}{\left(2\pi f n_1\right)^2 \cdot C_p} \tag{25}$$

where  $n_1$  is the dominant harmonic order which is equal to 5th  $(n_1 = 5)$  for three-phase three-wire system.

## B. Design of $L_{\rm PF}$ , $C_{\rm PF}$ , and $L_c$

The impedance of the SVC part is used to compensate the fundamental reactive power left by the CGCI part. The SVC part impedance can be expressed as follows:

$$X_{xy} = \frac{V_{xy}^2}{Q_{c1xy}} = \frac{3 \cdot \bar{V}_x^2}{Q_{c1xy}} = \frac{3 \cdot \bar{V}_x^2}{Q_{Lx} - Q_{LC}}$$
$$= \frac{\pi X_{L_{PF}} X_{C_{PF}}}{X_{C_{PF}} [2\pi - 2\alpha_{xy} + \sin(2\alpha_{xy})] - \pi X_{L_{PF}}} + X_{L_c}.$$
(26)

In (26),  $X_{Lc}$ ,  $X_{C_{\rm PF}}$ , and  $X_{L_{\rm PF}}$  are the fundamental impedances of  $L_c$ ,  $C_{\rm PF}$  and  $L_{\rm PF}$ . When  $\alpha_x = 180^\circ$  (thyristors are opened for the whole cycle), the SVC part has the maximum capacitive SVC impedance  $X_{xy}(\alpha_{xy} = 180^\circ)(<0)$ . At this situation, the SVC part can provide maximum capacitive reactive power  $Q_{cx(MaxCap)}$  for maximum inductive loads reactive power compensation  $Q_{Lx(MaxInd)}(=-Q_{cx(MaxCap)})$ . On the other hand, when  $\alpha_{xy} = 90^\circ$  (one of thyristors is closed for whole cycle), the SVC part has the minimum inductive SVC impedance  $X_{xy}(\alpha_x = 90^\circ)$ . The SVC part can provide maximum inductive reactive power  $Q_{cx(MaxInd)}$  for maximum capacitive loads reactive power compensation  $Q_{Lx(MaxCap)}$  $(= -Q_{cx(MaxInd)})$ . Based on above discussions and (26), the relationship among  $Q_{Lx(MaxCap)} Q_{Lx(MaxInd)}$  and coupling SVC impedance can be given by

$$\frac{3 \cdot V_x^2}{Q_{Lx(\text{MaxInd})} - Q_{LC}} = X_{xy}(\alpha_{xy} = 180^\circ) = -\frac{1}{X_{C_{\text{PF}}} - X_{L_c}}$$
(27)

$$\frac{3 \cdot V_x}{Q_{Lx(\text{MaxCap})} - Q_{LC}} = X_{xy} (\alpha_{xy} = 90^{\circ})$$
$$= \frac{X_{L_{\text{PF}}} X_{C_{\text{PF}}}}{X_{C_{\text{PF}}} - X_{L_{\text{PF}}}} + X_{L_c}.$$
(28)

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9



IABLE I
PARAMETERS OF IGCI AND SVC//CGCI USED FOR
SIMULATION CASE STUDIES

	Parameters	Physical values
System parameters	$V_{LL}, f, L_s$	191V, 50Hz,0.2mH
IGCI	L	5mH
SVC//IGCI	$L_c, L_{PF}, C_{PF}L_p$	5mH, 30mH,160uF, 5mH
SVC//CGCI	$L_c, L_{PF}, C_{PF}L_p, C_P$	5mH, 30mH,160uF, 5mH, 80uF

Based on (27) and (28), the parallel capacitor  $C_{\rm PF}$  and inductor  $L_{\rm PF}$  can be designed as follows:

$$C_{\rm PF} = \frac{Q_{Lx(\text{MaxInd})} - Q_{LC}}{\omega^2 L_c (Q_{Lx(\text{MaxInd})} - Q_{LC}) + 3 \cdot \omega \bar{V}_x^2}$$
(29)

$$L_{\rm PF} = \frac{3\bar{V}_x^2 + \omega L_c (Q_{Lx(MaxCap)} - Q_{LC})}{-\omega (Q_{Lx(MaxCap)} - Q_{LC}) + \omega^3 L_c C_{\rm PF}} (30)$$
$$(J_{Lx(MaxCap)} - Q_{LC}) + 3\omega^2 \bar{V}_x^2 C_{\rm PF}$$

where  $Q_{LC}$  can be found from (8).

The purpose of the  $L_c$  design is to mitigate the harmonic currents generated by the thyristors [13]. The thyristors of SVC part can be considered as a pair of bidirectional switches, which would generate low-order harmonic currents when the switches change their states. Through the harmonic currents rejection analysis, the  $L_c$  can be expressed as [13]

$$L_c = \frac{1}{(2\pi f n_2)^2 C_{\rm PF}} , \quad L_c = \frac{1}{(2\pi f n_3)^2 C_{\rm PF} - 1/L_{\rm PF}}$$
(31)

where the harmonic orders  $n_2$  and  $n_3$  mainly depend on the  $L_c$ ,  $L_{\rm PF}$ , and  $C_{\rm PF}$  values. For a three-phase three-wire system, there is no 3*n*th-order harmonic current and the common harmonic orders are  $6n \pm 1 \ge 5$  with  $n = 1, 2, 3 \ldots$ . To avoid the harmonic currents injection by the SVC part, it is suggested to tune  $n_2$  and  $n_3$  to be away from the  $6n \pm 1$ st-order and/or close to the 3rd order [13].

## V. SIMULATION CASE STUDIES OF THE PROPOSED SVC//CGCI

In this section, the simulation case studies are provided to show the advantages of the proposed SVC//CGCI in comparison with the conventional IGCI and SVC//IGCI. The control scheme of the IGCI is based on the instantaneous reactive power theory, which is valid for sinusoidal or nonsinusoidal (harmonic), balanced or unbalanced three-phase power systems [31]. The parameters of IGCI, SVC//IGCI and the proposed of SVC//CGCI and simulation setups are given in Table I. The selections of dc-link voltage of IGCI and CGCI are provided as follows.

The coupling fundamental impedances for traditional IGCI part and CGCI part are fixed as  $X_L(>0)$  and  $X_{Lp} - X_{Cp}(<0)$ . The relationships among the  $V_x$ ,  $V_{\text{inv}xf}$ ,  $I_{cx2f}$ , and the coupling impedance of the traditional IGCI and CGCI can be expressed as follows:

$$V_{\text{inv}xf(\text{IGCI})} = V_x + X_L \cdot I_{cx2f}$$
(32)

$$V_{\text{inv}xf(\text{CGCI})} = V_x + (X_{L_p} - X_{C_p}) \cdot I_{cx2f}$$
(33)

where  $X_L(>0)$  and  $X_{Lp} - X_{Cp}(<0)$  are the coupling impedance of IGCI and CGCI.  $I_{cx2f}$  is the compensating current passing through the coupling impedance. The  $X_L(>0)$  is a small inductive impedance and  $X_{Lp} - X_{Cp}(<0)$  is a large capacitive impedance. In (32), if the  $I_{cx2f}$  is the capacitive, the  $V_{invxf(IGCI)}$  for IGCI is larger than  $V_x$ . On the other hand, as (33), the  $V_{invxf(CGCI)}$  for CGCI is smaller than  $V_x$  due to large voltage drop of coupling *LC*. The fundamental dc-link voltage can be expressed as follows:

$$V_{\text{DC}f} \approx \sqrt{6} \cdot V_{\text{inv}xf} > \sqrt{6} \cdot V_x. \tag{34}$$

In (34), the scale of  $\sqrt{6} (= \sqrt{2} \cdot \sqrt{3})$  can be explained by the following two reasons: First, to guarantee the sufficient  $V_{\text{DC}f}$ , the peak value of fundamental inverter voltage need to be considered  $V_{\text{inv}xf(p)} > \sqrt{2} \cdot V_{\text{inv}xf}$ . Second, to transfer the phase voltage  $V_{\text{inv}xf}$  to line-to-line dc-link voltage, the scale of  $\sqrt{3}$  is required. According to (34), the dc-link voltage of IGCI for the 110 V system  $V_{\text{DC}f} > \sqrt{6} \cdot 110 = 270$  V. The required dc-link voltage of CGCI can be smaller than IGCI. In this section, the dc-link voltage of IGCI and CGCI part are set to be 300 V and 120 V, respectively.

From Fig. 5(a) and Table II, it can be seen that the conventional IGCI can compensate the power factor (PF) to close to unity from original 0.97 and 0.71 for the light harmonic loads and heavy harmonic loads, respectively. Meanwhile, the total harmonic distortion (THD<sub>*i*sx</sub>) has been improved to lower than 5.4% for light harmonic loads and 4.1% for heavy harmonic loads. The required  $V_{\rm DC}$  and  $I_{cx2}$  are about 300 V and 7.4 A, respectively.

Based on Fig. 5(b) and Table II, the proposed SVC//CGCI can also compensate the PF to unity for the light harmonic loads (PF = 0.97) and heavy harmonic loads (PF = 0.71), respectively. Meanwhile, the source current THD<sub>*isx*</sub> has been improved to lower than 6.1% and 5.1% for light loads with 28.8% and heavy loads with 10.7%, respectively. The required  $V_{\rm DC}$  and  $I_{cx2}$  are 120 V and 3.2 A, respectively.

During unbalanced loading case, from Fig. 6(a) and Table II, the source reactive power  $Q_{sx}$  can be compensated to about zero and the  $P_{sx}$  can compensated to be balanced (about 562 W) with  $P_{cx}^* = 70$  W. From Fig. 6(a), the PF and THD<sub>isx</sub> are improved to 0.99 and 15.6% (worst phase) for unbalanced loads after conventional IGCI compensation.

From Fig. 6(b) and Table II, the  $Q_{sx}$  can be compensated to about 18 var and the  $P_{sx}$  can be balanced to 560 W with  $P_{cx}^* = 70$  W. From Fig. 6(b), the PF and THD<sub>isx</sub> have been compensated to unity and 4.7% (worst phase).

On the other hand, from Fig. 6(c) and Table II, the  $Q_{sx}$  can be compensated from 586 var to about 12 var and the  $P_{sx}$  can be balanced to 555 W with  $P_{cx}^* = 70$  W. From Fig. 6(b), the PF and THD<sub>isx</sub> have been compensated to unity and 3.5% (worst phase). Compared with IGCI, the proposed SVC//CGCI has better THD<sub>isx</sub> compensating performance.

Compared with the compensation performance of IGCI  $(THD_{isx} > 15.0\%)$  in Fig. 6(a), the SVC//IGCI in Fig. 6(b) can obtain better THD<sub>isx</sub> performance  $(THD_{isx} < 5.0\%)$  due to the compensating current sharing by SVC part of the SVC//IGCI.



Fig. 5. Waveforms of load voltage, dc-link voltage, load current, inverter current, source current, load and injected reactive power, reference and injected active power for light and heavy harmonic loads compensation by using (a) IGCI and (b) the proposed SVC//CGCI.

Among the three compensators, the SVC//CGCI in Fig. 6(c) obtains the best THD<sub>*isx*</sub> (< 4.0%) performance. In addition, the required dc-link voltage of SVC//CGCI ( $V_{\rm DC} = 120$  V) is smaller than IGCI ( $V_{\rm DC} = 300$  V) and SVC//IGCI ( $V_{\rm DC} = 300$  V).

Based on Fig. 5, the active inverter capacity of the proposed SVC//CGCI is just 17.3% of IGCI and 38% of SVC//IGCI. The major compensating power capacity of SVC//CGCI is shared by the SVC part and the coupling *LC* of the CGCI. Based on [13]–[15], the costs of IGCI (or active inverter part), PPF and SVC are about \$60/kVA, \$18/kVA, and \$5/kVA, respectively. The cost

TABLE II SIMULATION RESULTS FOR DIFFERENT LOADS COMPENSATION BEFORE AND AFTER IGCI AND THE PROPOSED SVC//CGCI COMPENSATION

Loads	Compensation		PF	$THD_{isx}(\%)$	$P_{sx}(W)$	$Q_{\rm sx}(\rm var)$	$i_{invx}(A)$	$V_{DC}(\mathbf{V})$	
Light	Before comp.		0.97	28.3	442	20			
Harmonic	IGCI		1.00	5.4	308	9	1.3	300	
Loads	SVC//CGCI		1.00	6.1	308	7	3.0	120	
Heavy	eavy Before comp. nonic, IGCI		0.71	10.7	813	808			
Harmonic,			1.00	4.1	681	9	7.4	300	
Loads SVC//CGC		Ι	1.00	5.1	680	8	3.6	120	
Unbalanced Harmonic Loads	Before comp.	а	0.69	20.2	558	586			
		b	0.84	25.7	546	546			
		с	0.86	18.6	759	349			
	IGCI	а	0.99	15.6	558	12	5.4	300	
		b	0.99	3.5	560	14	4.8		
		с	0.99	1.9	567	13	3.4		
	SVC//IGCI	а	1.00	4.4	563	16	3.8		
		b	1.00	3.8	560	17	3.7	300	
		с	1.00	4.7	557	18	3.9		
	SVC//CGCI	а	1.00	3.4	558	12	3.8		
		b	1.00	3.5	550	11	3.5	120	
			1.00	1.9	557	10	3.9		

of SVC//CGCI can be approximately calculated as the sum of cost SVC, PPF, and 17.3% of IGCI. Based on the cost analysis, the cost of the IGCI, SVC//IGCI, and the proposed SVC//CGCI are estimated about 60/kVA, \$68.3/kVA, and \$33.4/kVA (just 56% of IGCI).

#### **VI. EXPERIMENTAL RESULTS**

In this section, an 110V-5 kVA experimental prototype of IGCI and SVC//CGCI with the proposed design method is built in laboratory. The photos of the experimental setup of the proposed SVC//CGCI and the different components are shown in Figs. 7 and 8. In Figs. 7 and 8, the digital control system of the SVC//CGCI is digital signal processor (DSP) TMS320F2812, and the sampling frequency of the control system is 25 kHz. The switching devices for the inverter are Mitsubishi insulated gate bipolar transistor (IGBT) intelligent power modules PM300DSA060. The switching devices for the SVC are thyristors SanRex PK110FG160. Moreover, the experimental parameters of the SVC//CGCI are approximately the same as simulation study, which are shown in Table I. During the startup process, the SVC part is turned on first. Until SVC part goes to steady state, the CGCI part is connected to system with the protection of series connected resistors. After the CGCI goes to the steady state, the protect resistors are bypassed.

Fig. 9 illustrates the waveforms of voltage and current by using the conventional IGCI. From Fig. 9(a) and Table III, for the inductive loading, the worst phase PF and THD<sub>*isx*</sub> have been improved from original 0.96 and 24.5% to 0.99 and 13.5% after IGCI compensation. From Fig. 9(b) and Table III, for the unbalanced loads compensation, the worst case PF and THD<sub>*isx*</sub> have been compensated to 0.98 and 15.4% after IGCI compensation. The dc-link voltage of IGCI is slightly larger than 300 V.

From Figs. 10, 11, and Table III, after SVC//CGCI compensation with  $V_{\rm DC} = 120$  V, the worst phase PF has been improved from 0.76 to 0.99. The worst phase THD<sub>*isx*</sub> has been kept to about 5.5% (worst phase). Since the proposed SVC//CGCI is connected to a low rating isolation transformer with inductive impedance, the load voltage is increased after reactive power



Fig. 6. Waveforms of load voltage, dc-link voltage, load current, source current, source reactive, and active powers for unbalanced harmonic loads compensation by using (a) IGCI, (b)SVC//CGCI, and (c) the proposed SVC//CGCI.



Fig. 7. Experimental setup of the SVC//CGCI experimental prototype.



Fig. 8. SVC//CGCI and loading system. (a) IGBTs and their divers. (b) Thyristors and their divers. (c) Transducers with signal conditioning circuits. (d) DSPs and their extension boards. (e) SVC part components, dc capacitor and discharge resistor. (f) Loading system.

compensation. From Fig. 12(a) and (b), after compensation, the load voltage and load active power are slightly increasing due to the inductive impedance of isolation transformer. Compared with load active power (710, 780, and 780 W) in Fig. 12(b), the source active power is reduced to 650 W, 690 W and 680 W after SVC//CGCI compensation as Fig. 12(c) with  $P_{cx}^* = 100$  W. From Fig. 12(d), it can be seen that reactive power are compensated from 650 var to 80 var for worst phase.

From Figs. 13, 14, and Table III, after SVC//CGCI compensation with  $V_{\rm DC} = 120$  V, the PF has been compensated from 0.69, 0.76, and 0.83 to 0.99 for three phases under unbalanced loads compensation. The source current THD<sub>isx</sub> has been improved to 9.8% for the worst phase. In Fig. 15, it can be seen that the load voltage and source current are in phase with each other after compensation even under unbalanced loads. From Fig. 16(b) and (c), after SVC//CGCI compensation, the source active power of three phases have been balanced to 620, 620, and 600 W. Compared with the load active power (660, 650, and 840 W), the total source active power is reduced due to active power injection by the CGCI part with  $P_{cx}^* = 70$  W. Meanwhile,





Fig. 9. Waveforms of  $v_x$  and  $i_{sx}$  by using IGCI for reactive power and harmonic compensation. (a) During inductive loads. (b) During unbalanced loads.

TABLE III EXPERIMENTAL RESULTS FOR DIFFERENT LOADS BEFORE AND AFTER SVC//CGCI COMPENSATION

			$Q_{sx}(var)$	$P_{sx}(W)$	PF	$THD_{isx}(\%)$	$V_{DC}(\mathbf{V})$
ive loads	Before Comp.	Α	650	700	0.77	5.7	
		В	650	740	0.76	5.9	
		С	650	740	0.77	5.9	
	IGCI	Α	70	690	0.99	12.3	320
		В	80	700	0.99	13.1	
uct		С	70	700	0.99	13.5	
Ind		Α	60	650	0.99	5.3	
	SVC//CGCI	В	50	690	0.99	5.4	120
		С	80	680	0.99	5.5	
	Before Comp. IGCI	Α	600	590	0.69	12.8	
ced		В	480	560	0.76	18.0	
and		С	520	780	0.83	14.0	
bal lo2		Α	70	640	0.98	15.4	
Un		В	90	630	0.98	15.3	320
		С	80	630	0.98	15.4	
	SVC//CGCI	A	10	620	0.99	8.4	120
		В	80	620	0.99	6.9	
		С	20	600	0.99	9.8	



Fig. 10. Waveforms of  $v_x$  and  $i_{sx}$  by using SVC//CGCI for active power injection and nonactive power compensation under inductive loads.



Fig. 11.  $i_{sx}$  harmonic spectrums of SVC//CGCI for harmonic loads compensation. (a) Before compensation. (b) After compensation.



Fig. 12. Waveforms before and after SVC//CGCI compensation for harmonic loads compensation. (a) Load voltage. (b) Load active power. (c) Source active power. (d) Source reactive power.

the source reactive power has been compensated from 600, 480, and 520 var to 10, 80, and 20 var, as shown in Fig. 16(d).

Compared the experiments results of the IGCI with the proposed SVC//CGCI, the SVC//CGCI obtains better compensation performances (PF and  $THD_{isx}$ ) with lower dc-link voltage.



Fig. 13. Waveforms of  $v_x$  and  $i_{sx}$  by using SVC//CGCI for active power injection and nonactive power compensation under unbalanced loads.



Fig. 14.  $i_{sx}$  harmonic spectrums of SVC//CGCI for unbalanced harmonic loads compensation. (a) Before compensation. (b) After compensation.



Fig. 15. Vector diagram of SVC//CGCI for unbalanced loads. (a) Before compensation. (b) After compensation.



Fig. 16. Waveforms before and after SVC//CGCI compensation for unbalanced loads. (a) Load voltage. (b) Load active power. (c) Source active power. (d) Source reactive power.

#### VII. CONCLUSION

In this paper, a new structure of SVC in parallel with CGCI (SVC//CGCI) in a three-phase power system was proposed and discussed as a cost-effective solution for active power injection and nonactive power (harmonic, reactive, and unbalanced power) compensation. The SVC part was used to dynamically compensate the reactive power and balance the source active power. The CGCI was used to compensate harmonic power and provide a fixed amount of reactive power (coupling LC). Finally, representative simulation and experimental results are provided to show that the SVC//CGCI has the great promise for wide operation range with both low voltage and current rating of active inverter.

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